

Evolving Fuzzy Models and Transportation Applications

Radu-Emil Precup

*Department of Automation and Applied Informatics
Politehnica University of Timisoara
Center for Fundamental and Advanced Technical Research
Romanian Academy-Timisoara Branch
Timisoara, Romania
radu.precup@upt.ro*

INVITED PRESENTATION

Abstract—As specified in the classic papers on evolving fuzzy systems due to Angelov and his co-authors back in 2001 and 2002, a specific feature of evolving fuzzy models in their either Mamdani or (Takagi-Sugeno or Takagi-Sugeno-Kang fuzzy) forms is the continuous online learning of the rule base. These fuzzy models are derived by online identification algorithms. The online identification algorithms continuously evolve the parameters in different subsystems of the fuzzy models, which are built online by adding new or removing old so-called “local” models. The local models are placed in the rule consequents, and this process is referred to as the adding mechanism.

The well-recognized classification of online identification algorithms by Dovžan, Logar, and Škrjanc in 2015 highlights three representative families of online identification algorithms, (i), (ii), and (iii): (i) adaptive algorithms – which start from the initial Takagi-Sugeno-Kang fuzzy model structure given by other algorithms (i.e., (ii) incremental algorithms – which implement adding mechanisms; (iii) evolving algorithms – these are the most advanced and fresh ones, as they implement, besides the adding mechanism, also removing and a part of them merging and splitting mechanisms.

The operating mechanisms of online identification algorithms briefly described above give valid explanations on the rather large area of nonlinear systems whose behavior is characterized in order to ensure both accurate modeling for simulation and model-based fuzzy control design. The scope of the development of these models is the model-based and data-driven model-free design and tuning of fuzzy controllers by the Process Control Group of the Politehnica University of Timisoara, Romania.

This presentation focuses on some of the results obtained by the Process Control Group in applications of evolving fuzzy models. The presentation covers some representative and recent applications implemented in the group’s laboratories, with real-world validation through experiments and detailed simulations. The results exemplified in this presentation concern several transportation applications, including the speed control of Connected Autonomous Electric Buses, taking into account the presence of human-driven vehicles, the anti-lock braking systems, and several servo systems.

This work was supported by a grant of the Ministry of Research, Innovation and Digitization, CNCS/CCCDI - UEFISCDI, project number ERANET-ENUAC-e-MATS, within PNCDI IV.

Keywords—*evolving fuzzy models, incremental algorithms, Takagi-Sugeno-Kang fuzzy models, transportation applications*

SHORT BIO

Radu-Emil Precup (M IEEE '03 - SM IEEE '07) was born in Lugoj, Romania, in 1963. He received the Dipl.Ing. (Hons.) degree in automation and computers from the "Traian Vuia" Polytechnic Institute of Timisoara, Timisoara, Romania, in 1987, the Diploma in mathematics from the West University of Timisoara, Timisoara, in 1993, and the Ph.D. degree in automatic systems from the "Politehnica" University of Timisoara, Timisoara, in 1996.

From 1987 to 1991, he was with Infoservice S.A., Timisoara. He is currently with the Politehnica University of Timisoara, Romania, where he became a Professor in the Department of Automation and Applied Informatics, in 2000, and he is currently a Doctoral Supervisor of automation and systems engineering. From 2022, he is also a senior researcher (CS I) and the head of the Data Science and Engineering Laboratory of the Center for Fundamental and Advanced Technical Research, Romanian Academy – Timisoara Branch, Romania. From 2016 to 2022, he was an Adjunct Professor within the School of Engineering, Edith Cowan University, Joondalup, WA, Australia. He is currently the Director of the Automatic Systems Engineering Research Centre with the Politehnica University of Timisoara, Romania. From 1999 to 2009, he held research and teaching positions with the Université de Savoie, Chambéry and Annecy, France, Budapest Tech Polytechnical Institution, Budapest, Hungary, Vienna University of Technology, Vienna, Austria, and Budapest University of Technology and Economics, Budapest, Hungary. He is an editorial board member of several prestigious journals including IEEE Transactions on Fuzzy Systems, IEEE Transactions on Cybernetics, Information Sciences (Elsevier), Engineering Applications of Artificial Intelligence (Elsevier), Applied Soft Computing (Elsevier), Expert Systems with Applications (Elsevier), Evolving Systems (Springer), Applied Artificial Intelligence (Taylor & Francis), Healthcare Analytics (Elsevier), and Communications in Transportation Research (Elsevier).

He is the author or coauthor of more than 300 papers published in various scientific journals, refereed conference proceedings, and contributions to books. His research interests include mainly development and analysis of new control structures and algorithms (conventional control,

fuzzy control, data-based control, sliding mode control, neuro-fuzzy control, etc.), theory and applications of soft computing, computer-aided design of control systems, modeling, optimization (including nature-inspired algorithms), and applications to mechatronic systems (including automotive systems and mobile robots), embedded systems, control of power plants, servo systems, electrical driving systems.

Prof. Precup is a corresponding member of The Romanian Academy, a Doctor Honoris Causa of the Óbuda University, Budapest, Hungary, a Doctor Honoris Causa of the Széchenyi István University, Győr, Hungary, a member of the Task Force on Autonomous Learning Systems within the Neural Networks Technical Committee (TC) of the Institute of Electrical and Electronics Engineers (IEEE) Computational Intelligence Society, the TCs on Computational Cybernetics, and Cyber-Medical Systems of the IEEE Systems, Man, and Cybernetics Society, the Task Force on Adaptive and Evolving Fuzzy Systems within the Fuzzy Systems TC of the IEEE Computational Intelligence Society, the TCs on Data-Driven Control and Monitoring, and Control, Robotics and Mechatronics of the IEEE Industrial Electronics Society, the International Federation of Automatic Control (IFAC) TC on Computational Intelligence in Control (previously named Cognition and Control), the IFAC TC on Linear Control Systems, the Working Group WG 12.9 on Computational Intelligence of the Technical Committee TC12 on Artificial Intelligence of the International Federation for Information Processing (IFIP), the European Society for Fuzzy Logic and Technology (EUSFLAT), the Hungarian Fuzzy Association, and the Romanian Society of Control Engineering and Technical Informatics. He founded in 2015 and is the chair of the IEEE Systems, Man, and Cybernetics Society Romania Chapter. He has been the chair of the Timisoara Branch of the Robotics Society of Romania since 2020.

He was the recipient of the Elsevier Scopus Award for Excellence in Global Contribution (2017), the "Tudor Tănăsescu" Prize from the Romanian Academy for data-driven controller tuning techniques (2020), the "Grigore Moisil" Prize from the Romanian Academy, two times, in 2005 and 2016, for his contribution on fuzzy control and the optimization of fuzzy systems, the Spiru Haret Award from the National Grand Lodge of Romania in partnership with the Romanian Academy in 2016 for education, environment and IT, the Excellency Diploma of the International Conference on Automation, Quality & Testing, Robotics AQTR 2004 (THETA 14, Cluj-Napoca, Romania), two Best Paper Awards in the Intelligent Control Area of the 2008 Conference on Human System Interaction HSI 2008, Krakow (Poland), the Best Paper Award of 16th Online World Conference on Soft Computing in Industrial Applications WSC16 (Loughborough University, UK) in 2011, the Certificate of Appreciation for the Best Paper in the Session TT07 1 Control Theory of 39th Annual Conference of the IEEE Industrial Electronics Society IECON 2013 (Vienna, Austria), a Best Paper Nomination at 12th International Conference on Informatics in Control, Automation and Robotics ICINCO 2015 (Colmar, France), a Best Paper Award at 7th International Conference on Information Technology and Quantitative Management ITQM 2019 (Granada, Spain), a Best Paper Award at 8th International Conference on Information Technology and Quantitative Management ITQM 2020 & 2021 (Chengdu, China), was named a 2022 academic data leader by Chief

Data Officer (CDO) Magazine, and was listed as one of the top 10 researchers in Artificial Intelligence and Automation (according to IIoT World as of July 2017).

SELECTED REFERENCES

- [1] P. Geethanjali, "Myoelectric control of prosthetic hands: state-of-the-art review," *Med. Dev. Evid. Res.*, vol. 9, pp. 247–255, Dec. 2016.
- [2] J.-H. Wang, H.-C. Ren, W.-H. Chen, and P. Zhang, "A portable artificial robotic hand controlled by EMG signal using ANN classifier," in *Proc. 2015 IEEE Int. Conf. Inform. Autom.*, Lijiang, China, 2015, pp. 2709–2714.
- [3] Z.-J. Xu, Y.-T. Tian, and L. Yang, "sEMG pattern recognition of muscle force of upper arm for intelligent bionic limb control," *J. Bionic Eng.*, vol. 12, no. 2, pp. 316–323, Apr. 2015.
- [4] H.-X. Cao, S.-Q. Sun, and K.-J. Zhang, "Modified EMG-based handgrip force prediction using extreme learning machine," *Soft Comput.*, vol. 21, no. 2, pp. 491–500, Jan. 2017.
- [5] Y. Guo, G. R. Naik, S. Huang, A. Abraham, and H. T. Nguyen, "Nonlinear multiscale maximal Lyapunov exponent for accurate myoelectric signal classification," *Appl. Soft Comput.*, vol. 36, pp. 633–640, Nov. 2015.
- [6] C.-G. Yang, J.-S. Chen, Z.-J. Ju, and A. S. K. Annamalai, "Visual servoing of humanoid dual-arm robot with neural learning enhanced skill transferring control," *Int. J. Humanoid Robot.*, vol. 15, no. 2, pp. 1–23, Apr. 2018.
- [7] T.-A. Teban, R.-E. Precup, T. E. Alves de Oliveira, and E. M. Petriu, "Recurrent dynamic neural network model for myoelectric-based control of a prosthetic hand," in *Proc. 2016 IEEE Int. Syst. Conf.*, Orlando, FL, USA, 2016, pp. 1–6.
- [8] T.-A. Teban, R.-E. Precup, E.-C. Lunca, A. Albu, C.-A. Bojan-Dragos, and E. M. Petriu, "Recurrent neural network models for myoelectric-based control of a prosthetic hand," in *Proc. 22nd Int. Conf. Syst. Theor. Control Comput.*, Sinaia, Romania, 2018, pp. 603–608.
- [9] R.-E. Precup, T.-A. Teban, T. E. Alves de Oliveira, and E. M. Petriu, "Evolving fuzzy models for myoelectric-based control of a prosthetic hand," in *Proc. 2016 IEEE Int. Conf. Fuzzy Syst.*, Vancouver, BC, Canada, 2016, pp. 72–77.
- [10] R.-E. Precup, T.-A. Teban, E. M. Petriu, A. Albu, and I.-C. Mituletu, "Structure and evolving fuzzy models for prosthetic hand myoelectric-based control systems," in *Proc. 26th Mediter. Conf. Control Autom.*, Zadar, Croatia, 2018, pp. 625–630.
- [11] R.-E. Precup, T.-A. Teban, A. Albu, A.-I. Szedlak-Stinean, and C.-A. Bojan-Dragos, "Experiments in incremental online identification of fuzzy models of finger dynamics," *Rom. J. Inform. Sci. Tech.*, vol. 21, no. 4, pp. 358–376, Dec. 2018.
- [12] M. Tabakov, K. Fonal, R. A. Abd-Alhameed, and R. Qahwaji, "Fuzzy bionic hand control in real-time based on electromyography signal analysis," in *Comput. Coll. Intell. ICCCI 2016*, N. T. Nguyen, L. Iliadis, Y. Manolopoulos, and B. Trawiński, Eds. Cham: Springer, Lecture Notes in Computer Science, vol. 9875, pp. 292–302, 2016.
- [13] M. Tabakov, K. Fonal, R. A. Abd-Alhameed, and R. Qahwaji, "Bionic hand control in real-time based on electromyography signal analysis," in *Trans. Comput. Coll. Intell. XXIX*, N. T. Nguyen and R. Kowalczyk, Eds. Cham: Springer, LNCS, vol. 10840, pp. 21–38, 2018.
- [14] X. Zhou and P. Angelov, "Real-time joint landmark recognition and classifier generation by an evolving fuzzy system," in *Proc. 2006 IEEE Int. Conf. Fuzzy Syst.*, 2006, Vancouver, BC, Canada, pp. 1205–1212.
- [15] X. Zhou and P. Angelov, "Autonomous visual self-localization in completely unknown environment using evolving fuzzy rule-based classifier," in *Proc. 2007 IEEE Symp. Comput. Intell. Secur. Def. Appl.*, Honolulu, HI, USA, 2007, pp. 131–138.
- [16] R. D. Baruah and P. Angelov, "Evolving local means method for clustering of streaming data," in *Proc. 2012 IEEE Int. Conf. Fuzzy Syst.*, Brisbane, QLD, Australia, 2012, pp. 1–8.
- [17] P. Angelov, "Outside the box: an alternative data analytics framework," *J. Autom. Mob. Robot. Intell. Syst.*, vol. 8, no. 2, pp. 29–35, Apr. 2014.

- [18] P. Angelov, I. Škrjanc, and S. Blažič, "Robust evolving cloud-based controller for a hydraulic plant," in *Proc. 2013 IEEE Conf. Evol. Adapt. Syst.*, Singapore, 2013, pp. 1–8.
- [19] S. Blažič, I. Škrjanc, and D. Matko, "A robust fuzzy adaptive law for evolving control systems," *Evol. Syst.*, vol. 5, pp. 3–10, Mar. 2014.
- [20] D. Leite, R. M. Palhares, V. C. S. Campos, and F. A. C. Gomide, "Evolving granular fuzzy model-based control of nonlinear dynamic systems," *IEEE Trans. Fuzzy Syst.*, vol. 23, no. 4, pp. 923–938, Aug. 2015.
- [21] E. Lughofer and M. Pratama, "Online active learning in data stream regression using uncertainty sampling based on evolving generalized fuzzy models," *IEEE Trans. Fuzzy Syst.*, vol. 26, no. 1, pp. 292–309, Feb. 2018.
- [22] P. Wide, E. M. Petriu, and M. Siegel, "Sensing and perception for rehabilitation and enhancement of human natural capabilities," in *Proc. 2010 IEEE Int. Works. Robot. Sens. Env.*, Phoenix, AZ, USA, 2010, pp. 75–80.
- [23] D. Dovžan, V. Logar, and I. Škrjanc, "Implementation of an evolving Fuzzy Model (eFuMo) in a monitoring system for a waste-water treatment process," *IEEE Trans. Fuzzy Syst.*, vol. 23, no. 5, pp. 1761–1776, Oct. 2015.
- [24] N. Kasabov, "ECOS: A framework for evolving connectionist systems and the eco learning paradigm," in *Proc. 5th Int. Conf. Neural Inf. Proc.*, Kitakyushu, Japan, 1998, pp. 1222–1235.
- [25] P. Angelov and D. Filev, "An approach to online identification of Takagi-Sugeno fuzzy models," *IEEE Trans. Syst., Man, Cybern. B, Cybern.*, vol. 34, no. 1, pp. 484–498, Feb. 2004.
- [26] J. V. Ramos and A. Dourado, "On line interpretability by rule base simplification and reduction," in *Proc. Eur. Symp. Intell. Technol. Hybrid Syst. Impl. Smart Adapt. Syst.*, Aachen, Germany, 2004, pp. 1–6.
- [27] T. Niemueller, S. Zug, S. Schneider, and U. Karras, "Knowledge-based instrumentation and control for competitive industry-inspired robotic domains," *Künst. Intell.*, vol. 30, no. 3–4, pp. 289–299, Oct. 2016.
- [28] E. Osaba, R. Carballedo, F. Díaz, E. Onieva, A. Masegosa, and A. Perallos, "Good practice proposal for the implementation, presentation, and comparison of metaheuristics for solving routing problems," *Neurocomput.*, vol. 271, pp. 2–8, Jan. 2018.
- [29] R. Radiša, N. Dučić, S. Manasijević, N. Marković, and Ž. Čojbašić, "Casting improvement based on metaheuristic optimization and numerical simulation," *Facta Univ. Ser. Mech. Eng.*, vol. 15, no. 3, pp. 397–411, Jul. 2017.
- [30] R.-E. Precup and R.-C. David, *Nature-Inspired Optimization Algorithms for Fuzzy Controlled Servo Systems*. Oxford, UK: Butterworth-Heinemann, Elsevier, 2019.
- [31] P. Korondi, H. Hashimoto, and V. Utkin, "Discrete sliding mode control of two mass system," in *Proc. 1995 IEEE Int. Symp. Ind. Electron.*, Athens, Greece, 1995, pp. 338–343.
- [32] R.-E. Precup and S. Preitl, *Fuzzy Controllers*. Timisoara: Editura Orizonturi Universitare, 1999.
- [33] R.-E. Precup and S. Preitl, "Development of fuzzy controllers with non-homogeneous dynamics for integral-type plants," *Electr. Eng.*, vol. 85, no. 3, pp. 155–168, Jul. 2003.
- [34] C. Pozna, R.-E. Precup, J. K. Tar, I. Škrjanc, and S. Preitl, "New results in modelling derived from Bayesian filtering," *Knowl.-Based Syst.*, vol. 23, no. 2, pp. 182–194, Mar. 2010.
- [35] Á. Takács, L. Kovács, I. J. Rudas, R.-E. Precup, and T. Haidegger, "Models for force control in telesurgical robot systems," *Acta Poly. Hung.*, vol. 12, no. 8, pp. 95–114, Dec. 2015.
- [36] R.-E. Precup, T.-A. Teban, and A. Albu, "Evolving fuzzy and neural network models of finger dynamics for prosthetic hand myoelectric-based control," in *Proc. 11th Int. Conf. Electron. Comput. Artif. Intell.*, Pitesti, Romania, 2019, pp. 1–8.
- [37] R.-E. Precup, T.-A. Teban, A. Albu, A.-B. Borlea, I. A. Zamfirache, and E. M. Petriu, "Evolving fuzzy models for prosthetic hand myoelectric-based control using weighted recursive least squares algorithm for identification," in *Proc. 2019 IEEE Int. Symp. Robot. Sens. Environ.*, Ottawa, ON, Canada, 2019, pp. 164–169.
- [38] A. Albu, R.-E. Precup, and T.-A. Teban, "Results and challenges of artificial neural networks used for decision-making in medical applications," *Facta Univ. Ser. Mech. Eng.*, vol. 17, no. 4, pp. 285–308, Dec. 2019.
- [39] R.-E. Precup, T.-A. Teban, A. Albu, A.-B. Borlea, I. A. Zamfirache, and E. M. Petriu, "Evolving fuzzy models for prosthetic hand myoelectric-based control," *IEEE Trans. Instrum. Meas.*, vol. 69, no. 7, pp. 4625–4636, Jul. 2020.
- [40] R.-E. Precup, R.-C. Roman, T.-A. Teban, A. Albu, E. M. Petriu, and C. Pozna, "Model-free control of finger dynamics in prosthetic hand myoelectric-based control systems," *Stud. Informat. Control*, vol. 29, no. 4, pp. 399–410, Dec. 2020.
- [41] D. Hladek, J. Vascak, and P. Sincak, "Hierarchical fuzzy inference system for robotic pursuit evasion task," in *Proc. 2008 6th Int. Symp. Mach. Intell. Informat.*, Herľany, Slovakia, 2008, pp. 273–277.
- [42] C. Pozna and R.-E. Precup, "Aspects concerning the observation process modelling in the framework of cognition processes," *Acta Poly. Hung.*, vol. 9, no. 1, pp. 203–223, Mar. 2012.
- [43] H. Costin and S. Bejinariu, "Medical image registration by means of a bio-inspired optimization strategy," *Comput. Sci. J. Moldova*, vol. 20, no. 2, pp. 178–202, Jun. 2012.
- [44] R.-E. Precup, T. Haidegger, S. Preitl, B. Benyó, A. S. Paul, and L. Kovács, "Fuzzy control solution for telesurgical applications," *Applied and Computational Mathematics*, vol. 11, no. 3, pp. 378–397, Sep. 2012.
- [45] H. Costin, "Fuzzy rules-based segmentation method for medical images analysis," *Int. J. Comput. Commun. Control*, vol. 8, no. 2, pp. 196–206, Apr. 2013.
- [46] K. Michail, K. M. Deliparaschos, S. G. Tzafestas, and A. C. Zolotas, "AI-based actuator/sensor fault detection with low computational cost for industrial applications," *IEEE Trans. Control Syst. Technol.*, vol. 24, no. 1, pp. 293–301, Jan. 2016.
- [47] I.-D. Borlea, R.-E. Precup, F. Dragan, and A.-B. Borlea, "Centroid update approach to K-means clustering," *Adv. Electr. Comput. Eng.*, vol. 17, no. 4, pp. 3–10, Dec. 2017.
- [48] L. Nyulászi, R. Andoga, P. Butka, L. Főző, R. Kovacs, and T. Moravec, "Fault detection and isolation of an aircraft turbojet engine using a multi-sensor network and multiple model approach," *Acta Poly. Hung.*, vol. 15, no. 2, pp. 189–209, Apr. 2018.
- [49] Z. C. Johanyák, "Fuzzy rule interpolation based model for student result prediction," *J. Intell. Fuzzy Syst.*, vol. 36, no. 2, pp. 999–1008, Apr. 2019.
- [50] A. Lucchini, S. Formentin, M. Corno, D. Piga, and S. M. Savaresi, "Torque vectoring for high-performance electric vehicles: a data-driven MPC approach," *IEEE Control Syst. Lett.*, vol. 4, no. 3, pp. 725–730, Jul. 2020.
- [51] M. Parigi Polverini, S. Formentin, L. Merzagora, and P. Rocco, "Mixed data-driven and model-based robot implicit force control: a hierarchical approach," *IEEE Trans. Control Syst. Technol.*, vol. 28, no. 4, pp. 1258–1271, Jul. 2020.
- [52] R.-E. Precup, E.-L. Hedrea, R.-C. Roman, E. M. Petriu, A.-I. Szedlak-Stinean, and C.-A. Bojan-Dracos, "Experiment-based approach to teach optimization techniques," *IEEE Trans. Educ.*, vol. 64, no. 2, pp. 88–94, May 2021.
- [53] E. Osaba, J. Del Ser, A. D. Martinez, J. L. Lobo, and F. Herrera, "AT-MFCGA: An adaptive transfer-guided multifactorial cellular genetic algorithm for evolutionary multitasking," *Inf. Sci.*, vol. 570, pp. 577–598, Sep. 2021.
- [54] R.-E. Precup, C.-A. Bojan-Dracos, E.-L. Hedrea, R.-C. Roman, and E. M. Petriu, "Evolving fuzzy models of shape memory alloy wire actuators," *Rom. J. Inf. Sci. Technol.*, vol. 24, no. 4, pp. 353–365, Dec. 2021.
- [55] R.-E. Precup, S. Preitl, and G. Faur, "PI predictive fuzzy controllers for electrical drive speed control: Methods and software for stable development," *Comput. Ind.*, vol. 52, no. 3, pp. 253–270, Dec. 2003.
- [56] R.-E. Precup and S. Preitl, "PI and PID controllers tuning for integral-type servo systems to ensure robust stability and controller robustness," *Electr. Eng.*, vol. 88, no. 2, pp. 149–156, Jan. 2006.
- [57] R.-E. Precup and S. Preitl, "Stability and sensitivity analysis of fuzzy control systems. Mechatronics applications," *Acta Poly. Hung.*, vol. 3, no. 1, pp. 61–76, Mar. 2006.
- [58] R.-E. Precup and S. Preitl, "PI-fuzzy controllers for integral plants to ensure robust stability," *Inform. Sci.*, vol. 177, no. 20, pp. 4410–4429, Oct. 2007.
- [59] P. Angelov and D. Filev, "On-line design of Takagi-Sugeno models," in *Fuzzy Sets and Systems – IFSA 2003*, T. Bilgiç, B. De Baets, and O. Kaynak, Eds. Berlin, Heidelberg, Lecture Notes in Computer Science, vol. 2715, pp. 576–584, 2003.

- [60] P. Angelov, J. Victor, A. Dourado, and D. Filev, "On-line evolution of Takagi-Sugeno fuzzy models," *IFAC Proc. Vol.*, vol. 37, no. 16, pp. 67–72, Sep. 2004.
- [61] E.-L. Hedrea, R.-E. Precup, E. M. Petriu, C.-A. Bojan-Dragos, and C. Hedrea, "Tensor product-based model transformation approach to cart position modeling and control in pendulum-cart systems," *Asian J. Control*, vol. 23, no. 3, pp. 1238–1248, May 2021.
- [62] S. I. Boucetta and Z. C. Johanyák, "Optimized ad-hoc multi-hop broadcast protocol for emergency message dissemination in vehicular ad-hoc networks," *Acta Polyt. Hung.*, vol. 19, no. 5, pp. 23–42, May 2022.
- [63] C.-B. Gale-Cazan, C.-A. Bojan-Dragos, R.-E. Precup, R.-C. Roman, E. M. Petriu, and A.-I. Szedlak-Stinean, "GWO-based modeling of an unstable transport system," *Proc. Comput. Sci.*, vol. 214, pp. 195–202, Aug. 2022.
- [64] R.-E. Precup, G. Duca, S. Travin, and I. Zinicovscaia, "Processing, neural network-based modeling of biomonitoring studies data and validation on Republic of Moldova data," *Proceedings of the Romanian Academy, Series A: Mathematics, Physics, Technical Sciences, Information Science*, vol. 23, no. 4, pp. 403–410, Dec. 2022.
- [65] I. Škrjanc, S. Blažič, and O. E. Agamennoni, "Interval fuzzy modeling applied to Wiener models with uncertainties," *IEEE Trans. Syst., Man, Cybern. B, Cybern.*, vol. 35, no. 5, pp. 1092–1095, Oct. 2005.
- [66] F. Matia, V. Jiménez, B. P. Alvarado, and R. Haber, "The fuzzy Kalman filter: Improving its implementation by reformulating uncertainty representation," *Fuzzy Sets Syst.*, vol. 402, pp. 78–104, Jan. 2021.
- [67] A.-I. Szedlak-Stinean, R.-E. Precup, E. M. Petriu, R.-C. Roman, E.-L. Hedrea, and C.-A. Bojan-Dragos, "Extended Kalman filter and Takagi-Sugeno fuzzy observer for a strip winding system," *Expert Syst. Appl.*, vol. 208, paper 118215, Dec. 2022.
- [68] A. Villalonga, E. Negri, G. Biscardo, F. Castaño, R. E. Haber, L. Fumagalli, and M. Macchi, "A decision-making framework for dynamic scheduling of cyber-physical production systems based on digital twins," *Annu. Rev. Control*, vol. 51, pp. 357–373, Dec. 2021.
- [69] C.-A. Bojan-Dragos, R.-E. Precup, E. M. Petriu, R.-C. Roman, E.-L. Hedrea, and A.-I. Szedlak-Stinean, "GWO-based optimal tuning of controllers for shape memory alloy wire actuators," *IFAC-PapersOnLine*, vol. 55, no. 15, pp. 39–44, Jul. 2022.
- [70] R.-C. Roman, R.-E. Precup, S. Preitl, A.-I. Szedlak-Stinean, C.-A. Bojan-Dragos, E.-L. Hedrea, and E. M. Petriu, "PI controller tuning via data-driven algorithms for shape memory alloy systems," *IFAC-PapersOnLine*, vol. 55, no. 40, pp. 181–186, Nov. 2022.
- [71] R.-C. Roman, R.-E. Precup, E. M. Petriu, and M. Muntyan, "Fictitious reference iterative tuning of discrete-time model-free control for tower crane systems," *Stud. Informat. Control*, vol. 32, no. 1, pp. 5–14, Mar. 2023.
- [72] S. M. Abramov, S. Travin, G. Duca, and R.-E. Precup, "New opportunities model for monitoring, analyzing and forecasting the official statistics on coronavirus disease pandemic," *Rom. J. Inf. Sci. Technol.*, vol. 26, no. 1, pp. 49–64, Mar. 2023.
- [73] G. Duca, S. Travin, I. Zinicovscaia, and R.-E. Precup, "Approach to evaluate the data of moss biomonitoring studies: preprocessing and preliminary ranking," *Rom. J. Inf. Sci. Technol.*, vol. 26, no. 3–4, pp. 276–288, Sep 2023.
- [74] I. A. Zamfirache, R.-E. Precup, and E. M. Petriu, "Q-learning, policy iteration and actor-critic reinforcement learning combined with metaheuristic algorithms in servo system control," *Facta Univ. Ser. Mech. Eng.*, vol. 21, no. 4, pp. 615–630, Dec. 2023.
- [75] I. A. Zamfirache, R.-E. Precup, and E. M. Petriu, "Adaptive reinforcement learning-based control using proximal policy optimization and slime mould algorithm with experimental tower crane system validation," *Appl. Soft Comput.*, vol. 160, paper 111687, Jul. 2024.
- [76] R.-C. Roman, R.-E. Precup, and E. M. Petriu, "Active disturbance rejection control for 3D crane systems," *Proc. Comput. Sci.*, vol. 242, pp. 976–983, Aug. 2024.
- [77] R.-E. Precup, R.-C. Roman, E.-L. Hedrea, E. M. Petriu, C.-A. Bojan-Dragos, and A.-I. Szedlak-Stinean, "Metaheuristic-based tuning of proportional-derivative learning rules for proportional-integral fuzzy controllers in tower crane system payload position control," *Facta Univ. Ser. Mech. Eng.*, vol. 22, no 4, pp. 567–582, Dec. 2024.
- [78] L. Yan, T. Zhao, X.-P. Xie, and R.-E. Precup, "OSSEFS: An online semi-supervised ensemble fuzzy system for data streams learning with missing values," *Expert Syst. Appl.*, vol. 225, paper 124695, Dec. 2024.