

Lecture 9. Multimedia buses

Inter-IC Sound (I2S). Domestic Digital Bus (D2B). Media Oriented System Transport (MOST)

Transporting audio-video data



- A particular use case in embedded system networks is the delivery of audiovideo data
- Specific requirements:
 - Higher datarates dictated by the volume of information that has to be transported
 - Reliable transmission required to maintain quality of the audio-video stream



Communication protocols for multimedia

- Inter-IC Sound (I2S)
- Domestic Digital Bus (D2B)
- Media Oriented System Transport (MOST)
- IEEE 1394 (FireWire)



Inter-IC Sound (I2S)

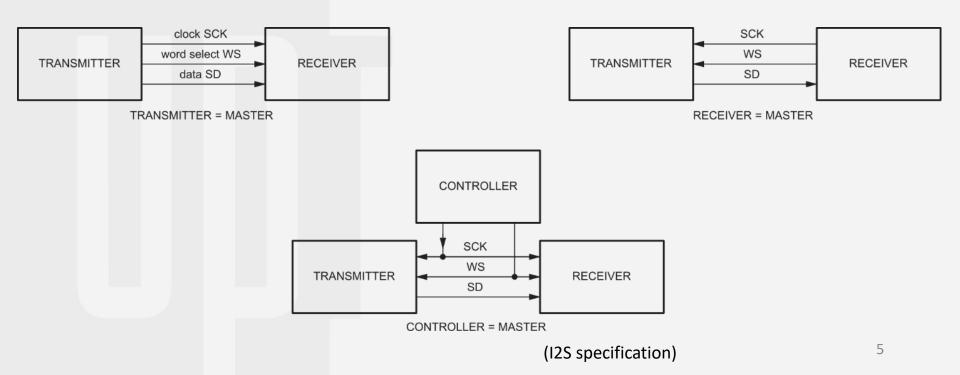


- Serial interface designed to transfer audio data
- Developed by Philips Semiconductors (Currently NXP)
- First specification published in February 1986, revised June 1996
- Uses 3 lines:
 - Serial Data (SD): Two time-multiplexed data channels
 - Word Select (WS): 0=left channel, 1 = right channel
 - Serial Clock (SCK): Clock
- Timing requirements are specified relative to the clock period or to the minimum allowed clock period of a device T_{tr} → data rates depend circuit clocking capabilities

I2S system configuration



- A master controls the SCK and WS lines
- The master role can be assumed by:
 - the transmitter node
 - the receiver node
 - a system master controller node



Serial data transmission

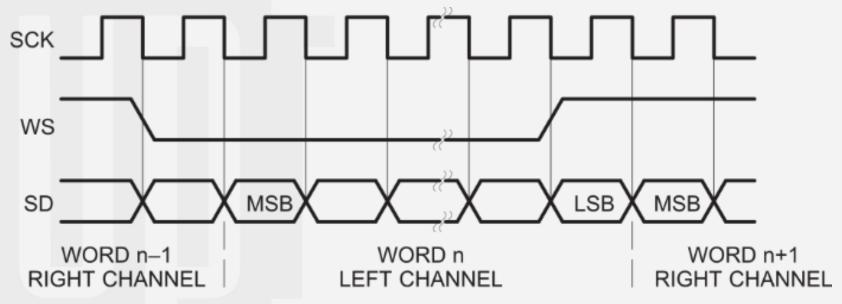


- Serial data is transmitted in two's complement
- MSB is transmitted first
- Transmitter and receiver may have different word lengths
 - System word length > receiver word length -> truncate received word
 - System word length < receiver word length -> append 0s for missing bits
 - System word length > transmitter word length -> missing bits set to 0
- Word length depend on implementation: 16-, 24-, 32-, 48- and 64-bit available in various I2S chips





- Transmitter always sends the MSB of the next word one clock period after WS changes
- Serial data sent by the transmitter may be synchronized with either the trailing (HIGH-to-LOW) or the leading (LOW-to-HIGH) edge of the SCK signal
- However, the serial data must be latched into the receiver on the leading edge of the SCK



Domestic Digital Bus (D2B)



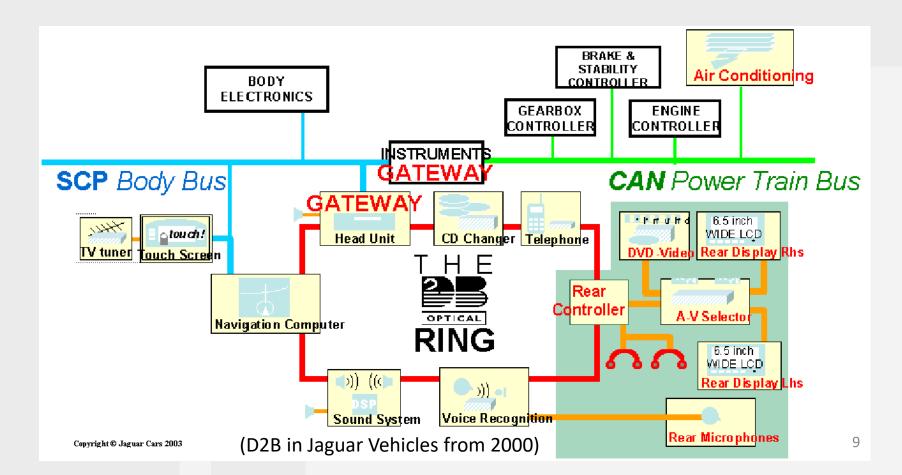
- Developed by Philips in the 1980s
- Standardised as IEC 61030 in 1991 but currently withdrawn and replaced with newer technology
- Multimaster communication
- Differential Twisted pair electrical conductor or optical fiber as transmission media

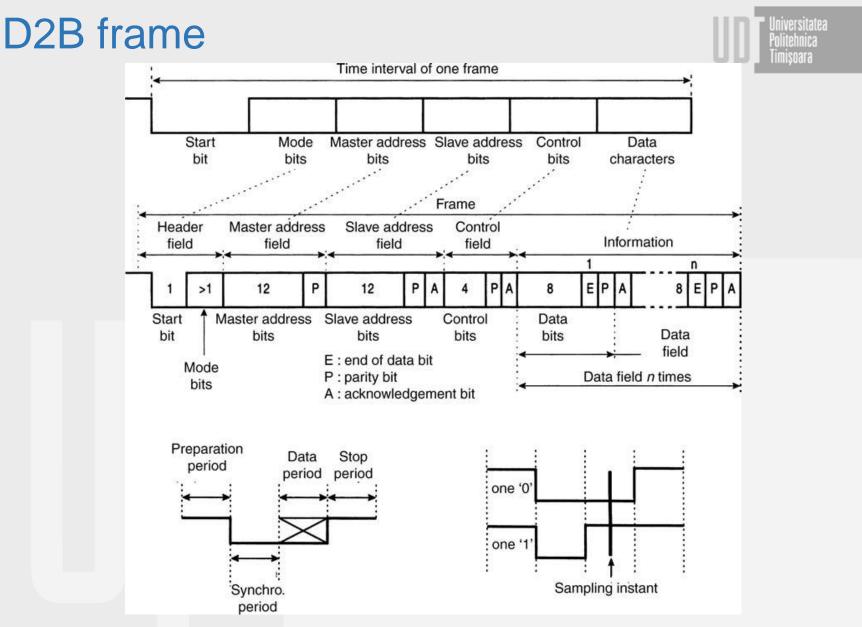


D2B Topology



- Daisy chain
- Optical ring





(D. Paret, Multiplexed Networks for Embedded Systems, Wiley, 2007) ¹⁰

Media Oriented Systems Transport (MO

- High-speed multimedia protocol
- Based on the D2B protocol



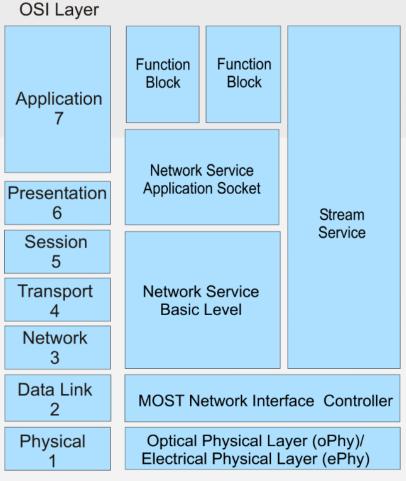
- Used by most of the major car manufacturers
- The MOST specification is developed and maintained by the MOST Cooperation organization

Main reference:

[MOST] Andreas Grzemba, *MOST, the automotive multimedia network*, Franzis Verlag, 2011

MOST mapped on the OSI model

- MOST protocol stack is mapped across all 7 OSI layers
- A high abstraction level enables fast system design
- Application is interfaced with the MOST stack through function blocks
- A function block provides the interface for controlling a particular functionality within a MOST node

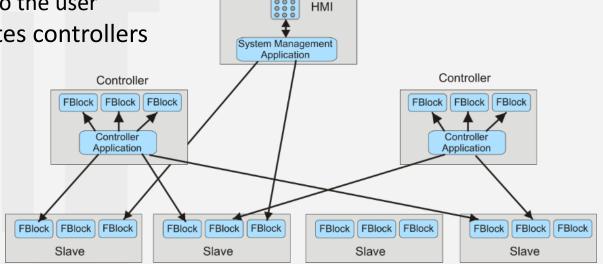


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Interactions in the MOST hierarchy



- Slave
 - device controlled by a controller but has no knowledge about the system
 - provides functionalities through its function blocks
- Controller ۲
 - administrates functionalities within a MOST system
 - requires knowledge about the subsystem it controls
- HMI (human-machine interface)
 - interface to the user •
 - coordinates controllers •



(after [MOST])

MOST physical layer



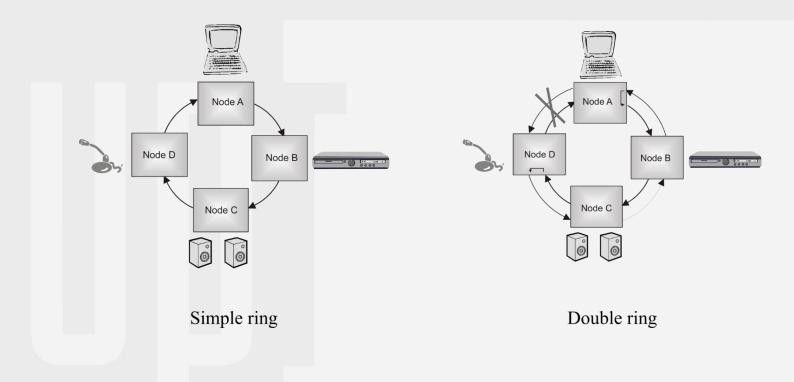
- Optical
 - uses Plastic Optic Fiber (POF)
 - Very good electromagnetic compatibility
- Electrical
 - Specified only for MOST50 and MOST 150

	MOST25	MOST50	MOST150
Bit rate	~25Mbit/s	~50Mbit/s	~150Mbit/s
Physical layer	Optical	Optical / Electrical	Optical/Electrical (based on coax line drivers)

MOST network topology



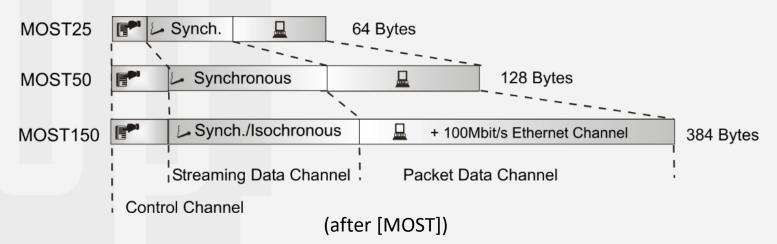
- Simple ring topology is the most commonly employed
- Double ring is used for increased availability in case of broken connections



MOST frames



- A MOST frame contains
 - one channel for the synchronous transmission of streaming data
 - one channel for the asynchronous transmission of packet data
 - one channel for the transmission of control data
- Streaming channel accommodates static connections between streaming sources and sinks
- Control channel general control messages for function blocks
- Packet data channel packet data such as configuration information



Timing masters/Timing slaves

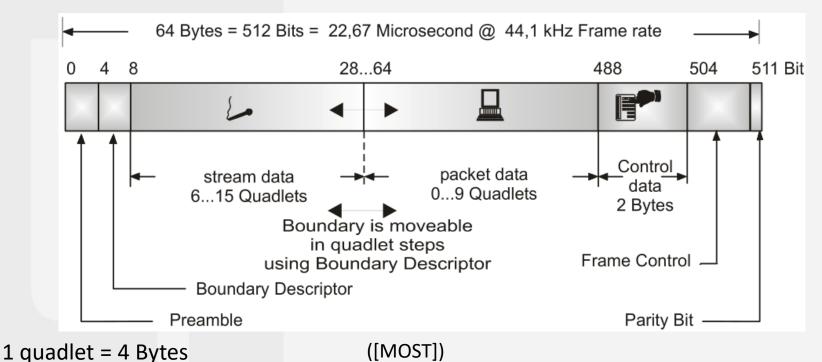


- Synchronization is achieved by a common system clock derived from the data stream
- System clock is generated by the Timing Master (usually implemented in the head unit of the infotainment system)
- All Timing Slaves are synchronized with the system clock pulse through a PLL connection
- The Timing Master receives the frame again after it travelled through the ring and generates the next frame
- Lock/Unlock state
 - a Timing Slave is in the lock state if it receives the input signal used to synchronize with the PLL
 - a Timing Master is in the lock state if it can regenerate the frame from the signal that travelled around the ring

MOST25 frame



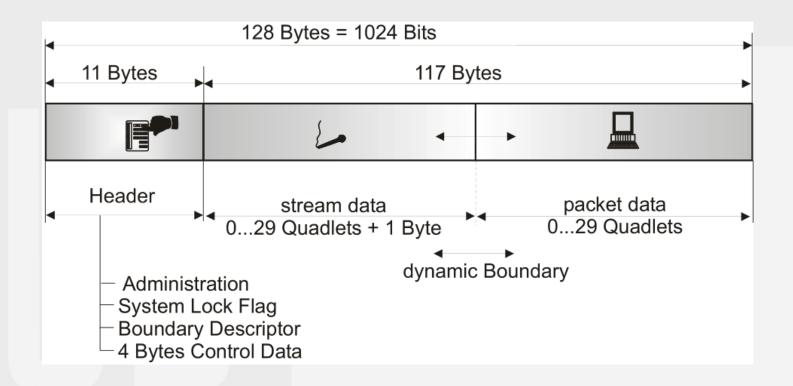
- Preamble used to synchronize TimingSlaves and initial frame identification
- Boundary descriptor used to adapt the bandwidth of the streaming and packet data channels
- Frame control holds frame control data and status bits
- Parity bit used for bit error detection



MOST50 frame



- Administration used for administrative data
- System Lock Flag indicated the system lock state



MOST150 frame



