Iterative Data-Driven Controller Tuning with Actuator Constraints and Reduced Sensitivity

By: Radac, MB (Radac, Mircea-Bogdan)[1] ; Precup, RE (Precup, Radu-Emil)[1] ; Petriu, EM (Petriu, Emil M.)[2] ; Preitl, S (Preitl, Stefan)[1]

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Abstract

This paper proposes a novel iterative data-driven alg
nonlinear systems. The iterative data-driven algorith
optimization problems for nonlinear processes, with
in terms of a quadratic penalty function approach. A
gradient information used in the search algorithm for
with respect to the controller parameters. A case stu
the angular position control of a nonlinear aerodynar
data-driven algorithm.

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Author Information

Reprint Address: Precup, RE (reprint author)

+ Politehn Univ Timisoara, Dept Automat & Appl I
Romania.

Addresses:

+ [1] Politehn Univ Timisoara, Dept Automat & Appl Informat, RO-300223 Timisoara, Romania

+ [2] Univ Ottawa, Sch Elect Engn & Comp Sci, Ottawa, ON K1N 6N5, Canada

E-mail Addresses: mircea.radac@aut.upt.ro; radu.precup@aut.upt.ro; petriu@uottawa.ca; stefan.preitl@aut.upt.ro

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