Data-Driven Reference Trajectory Tracking Algorithm and Experimental Validation

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IEEE TRANSACTIONS ON INDUSTRIAL INFORMA
Volume: 9 **Issue:** 4 **Pages:** 2327-2336
DOI: 10.1109/TII.2012.2220973
Published: NOV 2013
View Journal Impact

Abstract

This paper proposes a data-driven algorithm that sol
as an optimization problem. The new data-driven ref
solves the optimization problem in the framework of
updates the reference input sequence using an expe
operational constraints and employs an interior point
the advantages of data-driven control and ILC. A cas
control of a nonlinear servo system is included to val
results.

Keywords

Citation Network

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IEEE TRANSACTIONS ON INDUSTRIAL INFORMATICS

Impact Factor

6.764	7.538
2016	5 year

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AUTOMATION & CONTROL SYSTEMS	2 of 60	Q1
COMPUTER SCIENCE, INTERDISCIPLINARY APPLICATIONS	2 of 105	Q1
ENGINEERING, INDUSTRIAL	1 of 44	Q1

Data from the 2016 edition of Journal Citation Reports

Publisher

Author Keywords: Data-driven reference trajectory tuning; iterative learning control; lifted form represent

KeyWords Plus: ITERATIVE LEARNING CONTRO LOGIC CONTROLLER; BLAST-FURNACE; PREDIC IDENTIFICATION; PI

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Funding

Funding Agency	Grant Number
Romanian National Authority for Scientific Research, CNCS-UEFISCDI	PN-II-ID-PCE-2011-3-0109
NSERC of Canada	

View funding text

Publisher

IEEE-INST ELECTRICAL ELECTRONICS ENGINEERS INC, 445 HOES LANE, PISCATAWAY, NJ 08855-4141 USA

Categories / Classification

Research Areas: Automation & Control Systems; Computer Science; Engineering

Web of Science Categories: Automation & Control Systems; Computer Science, Interdisciplinary Applications; Engineering, Industrial

IEEE-INST ELECTRICAL ELECTRONICS ENGINEERS INC, 445 HOES LANE, PISCATAWAY, NJ 08855-4141 USA

ISSN: 1551-3203

eISSN: 1941-0050

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Language: English

Accession Number: WOS:000326113700052

ISSN: 1551-3203

eISSN: 1941-0050

Journal Information

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Other Information

IDS Number: 240RC

Cited References in Web of Science Core Collection: 62

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