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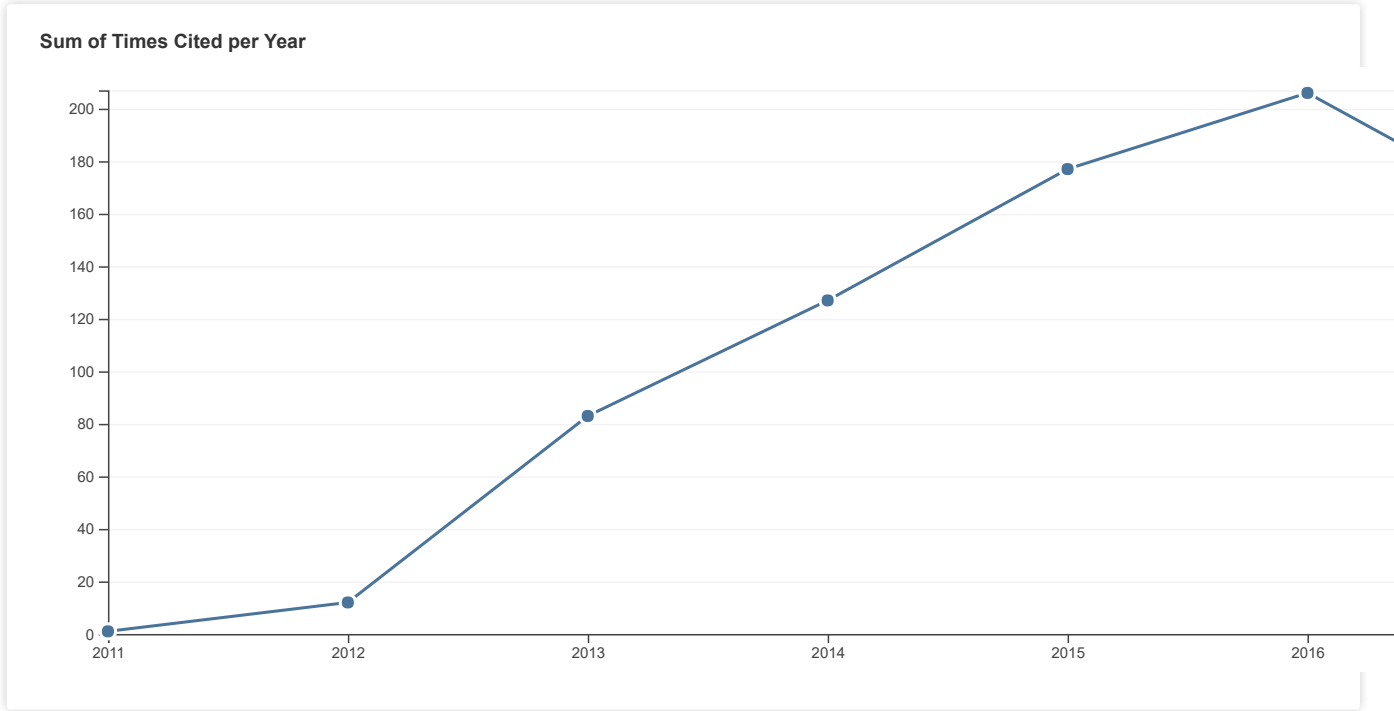
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- ☐ 31. **Evolving Fuzzy Models for the Position Control of Twin Rotor Aerodynamic Systems**
- By: Precup, Radu-Emil; Radac, Mircea-Bogdan; Petriu, Emil M.; et al.  
 Book Group Author(s): IEEE  
 Conference: 14th IEEE International Conference on Industrial Informatics (INDIN) Location: Poitiers, FRANCE Date: JUL 19-21, 2016  
 Sponsor(s): Inst Elect & Elect Engineers; IEEE Ind Elect Soc; Institut P; Univ Poitiers; CNRS  
 2016 IEEE 14TH INTERNATIONAL CONFERENCE ON INDUSTRIAL INFORMATICS (INDIN) Book Series: IEEE International Conference on Industrial Informatics INDIN Pages: 237-242 Published: 2016
- 0 0 0 4 0 4 2.00
- ☐ 32. **Two Data-Driven Control Algorithms for a MIMO Aerodynamic System with Experimental Validation**
- By: Roman, Raul-Cristian; Radac, Mircea-Bogdan; Precup, Radu-Emil; et al.  
 Edited by: Caraman, S; Barbu, M; Solea, R  
 Conference: 19th International Conference on System Theory, Control and Computing (ICSTCC) Location: ROMANIA Date: OCT 14-16, 2015  
 Sponsor(s): IEEE Control Syst Soc; Dunarea Jos Univ Galati, Fac Automat Control Comp Elect & Elect Engr; Univ Craiova, Fac Automat Comp & Elect; Gheorghe Asachi Tech Univ Iasi, Fac Automat Control & Comp Engr; NAPA; Natl Author Sci Res & Innovat, Minist Educ & Res Romania; Control Syst Comp & Elect Engr Soc; Romanian Soc Automat Control & Tech Informat  
 2015 19TH INTERNATIONAL CONFERENCE ON SYSTEM THEORY, CONTROL AND COMPUTING (ICSTCC) Pages: 736-741 Published: 2015
- 0 0 2 2 0 4 1.33
- ☐ 33. **Implementation of Evolving Fuzzy Models of a Nonlinear Process**
- By: Precup, Radu-Emil; Voisan, Emil-Ioan; Petriu, Emil M.; et al.  
 Edited by: Filipe, J; Madani, K; Gusikhin, O; et al.  
 Conference: 12th International Conference on Informatics in Control Automation and Robotics (ICINCO) Location: Alsace, FRANCE Date: JUL 21-23, 2015  
 Sponsor(s): Inst Syst & Technologies Informat Control & Commun; Univ Upper Alsace; IEEE Control Syst Soc; IEEE Robot & Automat Soc; Int Federat Automat Control; EUROMICRO; Assoc Advancement Artificial Intelligence; Associacao Portuguesa Controlo Automatico; Int Neural Network Soc; Asia Pacific Neural Network Assembly; euRobot; ACM Special Interest Grp Artificial Intelligence; AISBL  
 ICIMCO 2015 PROCEEDINGS OF THE 12TH INTERNATIONAL CONFERENCE ON INFORMATICS IN CONTROL, AUTOMATION AND ROBOTICS, VOL. 1 Pages: 5-14 Published: 2015
- 0 0 2 2 0 4 1.33
- ☐ 34. **Performance Analysis of Torque Motor Systems with PID Controllers Tuned by Bacterial Foraging Optimization Algorithms**
- By: Precup, Radu-Emil; Borza, Andrei-Leonard; Radac, Mircea-Bogdan; et al.  
 Book Group Author(s): IEEE  
 Conference: IEEE International Conference on Computational Intelligence and Virtual Environments for Measurement Systems and Applications (CIVEMSA) Location: Ottawa, CANADA Date: MAY 05-07, 2014  
 Sponsor(s): IEEE; IEEE Computat Intelligence Soc; IEEE Instrumentat & Measurement Soc  
 2014 IEEE INTERNATIONAL CONFERENCE ON COMPUTATIONAL INTELLIGENCE AND VIRTUAL ENVIRONMENTS FOR MEASUREMENT SYSTEMS AND APPLICATIONS (CIVEMSA) Book Series: IEEE International Conference on Computational Intelligence and Virtual Environments for Measurement Systems and Applications Pages: 141-146 Published: 2014
- 0 3 0 1 0 4 1.00
- ☐ 35. **Data-Driven Model-Free Adaptive Control of Twin Rotor Aerodynamic Systems**
- By: Roman, Raul-Cristian; Radac, Mircea-Bogdan; Precup, Radu-Emil  
 Edited by: Szakal, A  
 Conference: 9th IEEE International Symposium on Applied Computational Intelligence and Informatics (SACI) Location: Timisara, ROMANIA Date: MAY 15-17, 2014  
 Sponsor(s): IEEE  
 2014 IEEE 9TH INTERNATIONAL SYMPOSIUM ON APPLIED COMPUTATIONAL INTELLIGENCE AND INFORMATICS (SACI) Pages: 25-30 Published: 2014
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- ☐ 36. **EXPERIMENTS IN FUZZY CONTROLLER TUNING BASED ON AN ADAPTIVE GRAVITATIONAL SEARCH ALGORITHM**
- By: Precup, Radu-Emil; David, Radu-Codrut; Petriu, Emil M.; et al.  
 PROCEEDINGS OF THE ROMANIAN ACADEMY SERIES A-MATHEMATICS  
 PHYSICS TECHNICAL SCIENCES INFORMATION SCIENCE Volume: 14  
 Issue: 4 Pages: 360-367 Published: OCT-DEC 2013
- 4 0 0 0 0 4 0.80
- ☐ 37. **Stable Iterative Correlation-Based Tuning Algorithm for Servo Systems**
- By: Radac, Mircea-Bogdan; Precup, Radu-Emil; Petriu, Emil M.; et al.  
 Book Group Author(s): IEEE Industrial Electronics Society  
 Conference: 38th Annual Conference on IEEE-Industrial-Electronics-Society (IECON ) Location: Univ Quebec, Ecole Technologie Superieure Montreal (ETS), Montreal, CANADA Date: OCT 25-28, 2012  
 Sponsor(s): IEEE; IEEE Ind Elect Soc (IES)  
 38TH ANNUAL CONFERENCE ON IEEE INDUSTRIAL ELECTRONICS SOCIETY (IECON 2012) Book Series: IEEE Industrial Electronics Society  
 Pages: 2500-2505 Published: 2012
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- ☐ 38. **Linear and Fuzzy Control Solutions for a Laboratory Anti-lock Braking System**
- By: Radac, M. -B.; Precup, R. -E.; Preitl, S.; et al.  
 Book Group Author(s): IEEE  
 Conference: 6th International Symposium on Intelligent Systems and Informatics Location: Subotica, SERBIA Date: SEP 26-27, 2008  
 Sponsor(s): IEEE  
 2008 6TH INTERNATIONAL SYMPOSIUM ON INTELLIGENT SYSTEMS AND INFORMATICS Book Series: International Symposium on Intelligent Systems and Informatics Pages: 228-+ Published: 2008
- 2 2 0 0 0 4 0.40
- ☐ 39. **Three-level hierarchical model-free learning approach to trajectory tracking control**
- By: Radac, Mircea-Bogdan; Precup, Radu-Emil  
 ENGINEERING APPLICATIONS OF ARTIFICIAL INTELLIGENCE Volume: 55  
 Pages: 103-118 Published: OCT 2016
- 0 0 1 2 0 3 1.50
- ☐ 40. **Multi-input-multi-output system experimental validation of model-free control and virtual reference feedback tuning techniques**
- By: Roman, Raul-Cristian; Radac, Mircea-Bogdan; Precup, Radu-Emil  
 IET CONTROL THEORY AND APPLICATIONS Volume: 10 Issue: 12  
 Special Issue: SI Pages: 1395-1403 Published: AUG 8 2016
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