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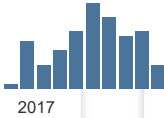
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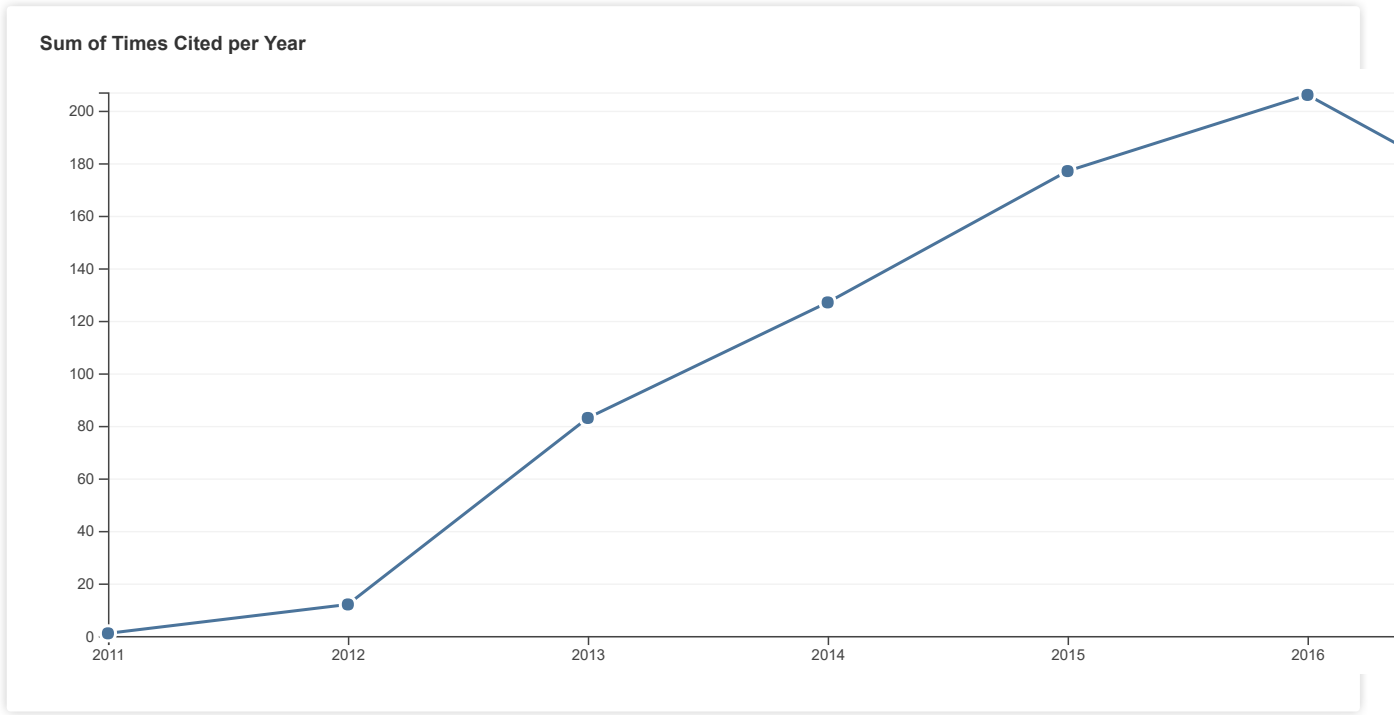
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- By: Precup, Radu-Emil; Radac, Mircea-Bogdan; Filip, Horatiu-I.; et al.
 Book Group Author(s): IEEE
 Conference: 29th Annual IEEE International Instrumentation and Measurement Technology Conference (I2MTC) Location: Graz, AUSTRIA Date: MAY 13-16, 2012
 Sponsor(s): IEEE; IEEE Instrumentat & Measurement Soc; IEEE Austria Sect; TU Graz; Virtual Vehicle Competence Ctr; Obuda Univ; European Acad Sci & Arts; Austrian Acad Sci; Int Soc Petr Engineers, Drilling Syst Automat Tech Sect; Arbeitskreis Hochschullehrer Messtechnik e.V. (AHMT); Joanneum Res; Austrian Ctr Competence Mechatron (ACCM); Platform Artemis Austria
 2012 IEEE INTERNATIONAL INSTRUMENTATION AND MEASUREMENT TECHNOLOGY CONFERENCE (I2MTC) Book Series: IEEE Instrumentation and Measurement Technology Conference Pages: 812-815 Published: 2012
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- ☐ 82. **Novel Iterative Formulation of Correlation-Based Tuning**
- By: Cerveneak, Bogdan-Stefan; Radac, Mircea-Bogdan; Precup, Radu-Emil; et al.
 Book Group Author(s): IEEE
 Conference: IEEE International Conference on Industrial Technology (ICIT) Location: Athens, GREECE Date: MAR 19-21, 2012
 Sponsor(s): Inst Elect & Elect Engineers Inc (IEEE); Ind Elect Soc (IES); Univ Patras; Ind Syst Inst (ISI); IEEE, Advancing Technol Human
 2012 IEEE INTERNATIONAL CONFERENCE ON INDUSTRIAL TECHNOLOGY (ICIT) Pages: 886-891 Published: 2012
- 0 0 0 0 0 0 0.00
- ☐ 83. **2-DOF PI(D) Takagi-Sugeno and Sliding Mode Controllers for BLDC Drives**
- By: Stinean, Alexandra-Iulia; Preitl, Stefan; Precup, Radu-Emil; et al.
 Book Group Author(s): IEEE
 Conference: 15th International Power Electronics and Motion Control Conference and Exposition (EPE-PEMC ECCE Europe) Location: Novi Sad, SERBIA Date: SEP 04-06, 2012
 Sponsor(s): Univ Novi Sad, Fac Tech Sci; Prov Secretariat Sci & Technol Dev & High Educ AP Vojvodina; Minist Educ Sci & Technol Dev Repub Serbia; IEEE PELS
 2012 15TH INTERNATIONAL POWER ELECTRONICS AND MOTION CONTROL CONFERENCE (EPE/PEMC) Published: 2012
- 0 0 0 0 0 0 0.00
- ☐ 84. **Stable Iterative Feedback Tuning Method for Servo Systems**
- By: Radac, Mircea-Bogdan; Precup, Radu-Emil; Petriu, Emil M.; et al.
 Book Group Author(s): IEEE
 Conference: 20th IEEE International Symposium on Industrial Electronics (ISIE) Location: Gdansk, POLAND Date: JUN 27-30, 2011
 Sponsor(s): Inst Elect & Elect Engineers (IEEE); IEEE Ind Elect Soc (IES); Gdansk Univ Technol
 2011 IEEE INTERNATIONAL SYMPOSIUM ON INDUSTRIAL ELECTRONICS (ISIE) Published: 2011
- 0 0 0 0 0 0 0.00
- ☐ 85. **2-DOF PI-FUZZY CONTROLLERS FOR A MAGNETIC LEVITATION SYSTEM**
- By: Dragos, Claudia-Adina; Precup, Radu-Emil; Petriu, Emil M.; et al.
 Edited by: Ferrier, JL; Bernard, A; Gusikhin, O; et al.
 Conference: 8th International Conference on Informatics in Control, Automation and Robotics Location: Noordwijkerhout, NETHERLANDS Date: JUL 28-31, 2011
 Sponsor(s): Inst Syst & Technol Informat Control & Commun; Inst Elect & Elect Engrn; IEEE, Robot & Automat Soc
 ICINCO 2011: PROCEEDINGS OF THE 8TH INTERNATIONAL CONFERENCE ON INFORMATICS IN CONTROL, AUTOMATION AND ROBOTICS, VOL 1 Pages: 111-116 Published: 2011
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- ☐ 86. **ITERATIVE LEARNING CONTROL APPLICATION TO A 3D CRANE SYSTEM**
- By: Precup, Radu-Emil; Enache, Florin-Cristian; Radac, Mircea-Bogdan; et al.
 Edited by: Ferrier, JL; Bernard, A; Gusikhin, O; et al.
 Conference: 8th International Conference on Informatics in Control, Automation and Robotics Location: Noordwijkerhout, NETHERLANDS Date: JUL 28-31,
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Sponsor(s): Inst Syst & Technol Informat Control & Commun; Inst Elect & Elect Engrn; IEEE, Robot & Automat Soc
 ICINCO 2011: PROCEEDINGS OF THE 8TH INTERNATIONAL CONFERENCE ON INFORMATICS IN CONTROL, AUTOMATION AND ROBOTICS, VOL 1 Pages: 117-122 Published: 2011

- ☐ 87. **Model-based Fuzzy Control Solutions for a Laboratory Antilock Braking System**
- By: Precup, Radu-Emil; Spataru, Sergiu Viorel; Radac, Mircea-Bogdan; et al.
 Edited by: Pardela, T; Wilamowski, B
 Conference: 3rd Annual International Conference on Human System Interaction (HSI) Location: Rzeszow, POLAND Date: MAY 13-15, 2010
 Sponsor(s): IEEE; Univ Informat Technol & Management; IES
 3RD INTERNATIONAL CONFERENCE ON HUMAN SYSTEM INTERACTION
 Book Series: Conference on Human System Interaction Pages: 133-138
 Published: 2010
- 0 0 0 0 0 0 0.00
- ☐ 88. **Iterative Learning Control Experimental Results for Inverted Pendulum Crane Mode Control**
- By: Precup, R. -E.; Gavrilita, C.; Radac, M. -B.; et al.
 Book Group Author(s): IEEE
 Conference: 7th International Symposium on Intelligent Systems and Informatics Location: Subotica, SERBIA Date: SEP 25-26, 2009
 Sponsor(s): IEEE
 2009 7TH INTERNATIONAL SYMPOSIUM ON INTELLIGENT SYSTEMS AND INFORMATICS Pages: 292-+ Published: 2009
- 0 0 0 0 0 0 0.00
- ☐ 89. **Signal Processing Aspects in State Feedback Control Based on Iterative Feedback Tuning**
- By: Radac, Mircea-Bogdan; Precup, Radu-Emil; Preitl, Stefan; et al.
 Book Group Author(s): IEEE
 Conference: 2nd Conference on Human System Interactions Location: Catania, ITALY Date: MAY 21-23, 2009
 Sponsor(s): Univ Catania, Dept Comp Engrn & Telecommun; IEEE Ind Elect Soc; Univ Informat Technol & Management; ST; iconics; Schneider
 HSI: 2009 2ND CONFERENCE ON HUMAN SYSTEM INTERACTIONS Book Series: Conference on Human System Interaction Pages: 37-42 Published: 2009
- 0 0 0 0 0 0 0.00
- ☐ 90. **ITERATIVE FEEDBACK TUNING APPROACH TO A CLASS OF STATE FEEDBACK-CONTROLLED SERVO SYSTEMS**
- By: Radac, Mircea-Bogdan; Precup, Radu-Emil; Petriu, Emil M.; et al.
 Edited by: Filipe, J
 Conference: 6th International Conference on Informatics in Control, Automation and Robotics Location: Milan, ITALY Date: JUL 02-05, 2009
 Sponsor(s): Inst Syst & Technologies Informat, Control & Commun; IFAC; Assoc Adv Artificial Intelligence
 ICINCO 2009: PROCEEDINGS OF THE 6TH INTERNATIONAL CONFERENCE ON INFORMATICS IN CONTROL, AUTOMATION AND ROBOTICS, VOL 1: INTELLIGENT CONTROL SYSTEMS AND OPTIMIZATION Pages: 41-+ Published: 2009
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