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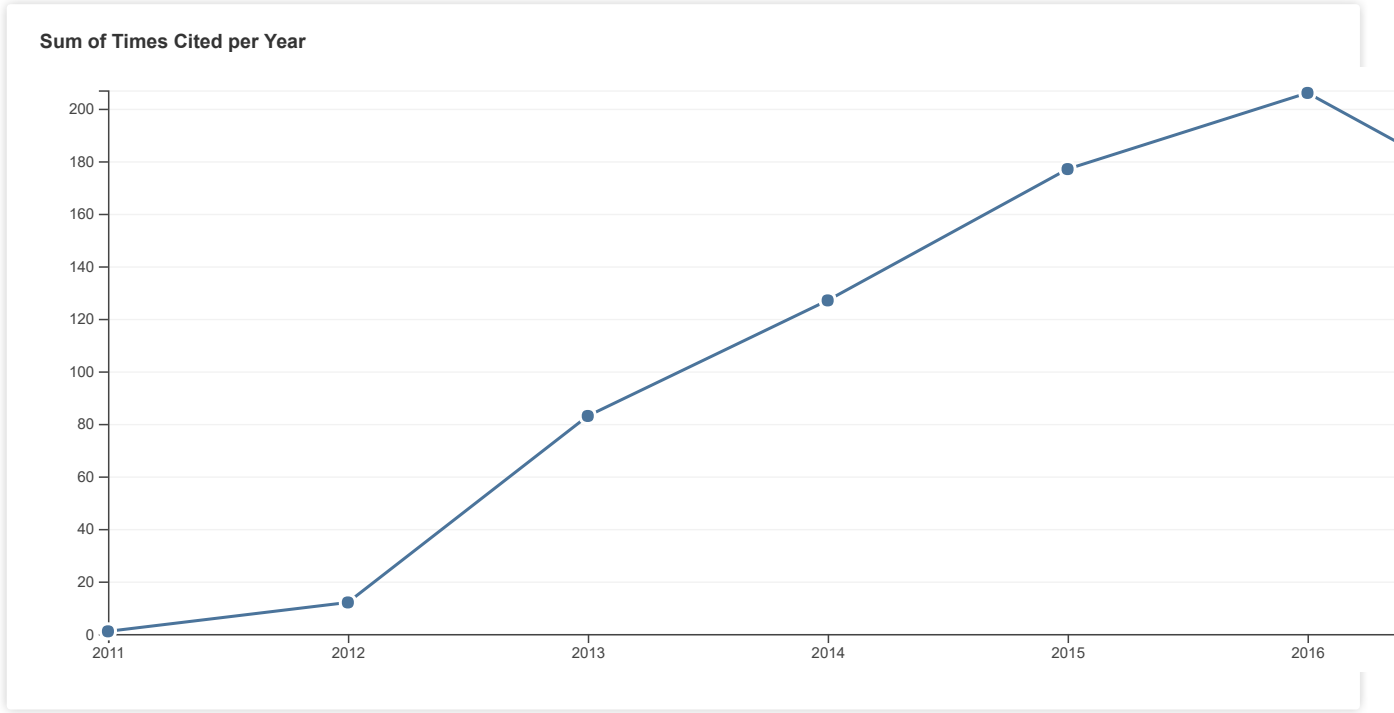
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- ☐ 71. **Data-Driven Virtual Reference Feedback Tuning and Reinforcement Q-learning for Model-Free Position Control of an Aerodynamic System**
- By: Radac, Mircea-Bogdan; Precup, Radu-Emil; Roman, Raul-Cristian
 Book Group Author(s): IEEE
 Conference: 24th Mediterranean Conference on Control and Automation (MED) Location: Athens, GREECE Date: JUN 21-24, 2016
 Sponsor(s): Mediterranean Control Assoc; IEEE Robot & Automat Soc; CSS; IEEE; ICUAS; IEEE Control Syst Soc
 2016 24TH MEDITERRANEAN CONFERENCE ON CONTROL AND AUTOMATION (MED) Book Series: Mediterranean Conference on Control and Automation Pages: 1126-1132 Published: 2016
- 0 0 0 0 0 0 0.00
- ☐ 72. **Improving Model Reference Control Performance Using Model-Free VRFT and Q-Learning**
- By: Radac, Mircea-Bogdan; Precup, Radu-Emil
 Edited by: Petre, E; Brezovan, M
 Conference: 20th International Conference on System Theory, Control and Computing (ICSTCC) Location: Sinaia, ROMANIA Date: OCT 13-15, 2016
 Sponsor(s): Inst Elect & Elect Engineers; Control Syst Soc; Univ Craiova, Fac Automat Comp Elect, Automat Control Res Ctr; Gheorghe Asachi Tech Univ Iasi, Fac Automat Control & Comp Engr; Dunarea Jos Univ Galati, Fac Control Syst Comp Elect & Elect Engr; Minist Educ & Res Romania, Natl Authority Sci Res & Innovat; IEEE Romanian Sect; Romanian Acad Tech Sci; Romanian Soc Automat & Tech Informat
 2016 20TH INTERNATIONAL CONFERENCE ON SYSTEM THEORY, CONTROL AND COMPUTING (ICSTCC) Book Series: International Conference on System Theory Control and Computing Pages: 7-13 Published: 2016
- 0 0 0 0 0 0 0.00
- ☐ 73. **Experiment-Based Comparison of Nature-Inspired Algorithms for Optimal Tuning of PI-Fuzzy Controlled Nonlinear DC Servo Systems**
- By: Precup, Radu-Emil; David, Radu-Codrut; Radac, Mircea-Bogdan; et al.
 Book Group Author(s): IEEE
 Conference: International Symposium on Power Electronics, Electrical Drives, Automation and Motion (SPEEDAM) Location: Capri, ITALY Date: JUN 22-24, 2016
 2016 INTERNATIONAL SYMPOSIUM ON POWER ELECTRONICS, ELECTRICAL DRIVES, AUTOMATION AND MOTION (SPEEDAM) Pages: 1261-1266 Published: 2016
- 0 0 0 0 0 0 0.00
- ☐ 74. **Adaptive Evolutionary Optimization Algorithms for Simple Fuzzy Controller Tuning Dedicated to Servo Systems**
- By: David, Radu-Codrut; Precup, Radu-Emil; Petriu, Emil M.; et al.
 Edited by: Matia, F; Marichal, GN; Jimenez, E
 FUZZY MODELING AND CONTROL: THEORY AND APPLICATIONS Book Series: Atlantis Computational Intelligence Systems Volume: 9 Pages: 159-173 Published: 2014
- 0 0 0 0 0 0 0.00
- ☐ 75. **Particle Swarm Optimization of Fuzzy Models for Anti-lock Braking Systems**
- By: Precup, Radu-Emil; Sabau, Marius-Csaba; Dragos, Claudia-Adina; et al.
 Edited by: Angelov, P; Filev, D; Kasabov, N; et al.
 Conference: IEEE Conference on Evolving and Adaptive Intelligent Systems (EAIS) Location: Linz, AUSTRIA Date: JUN 02-04, 2014
 Sponsor(s): IEEE; IEEE Syst, Man, & Cybernet Soc, Tech Comm Evolving Intelligent Syst; Linz Ctr Mechatron GmbH; Software Competence Ctr Hagenberg; Johannes Kepler Univ Linz; Fuzzy Log Lab Linz Hagenberg, Dept Knowledge Based Math Syst
 2014 IEEE CONFERENCE ON EVOLVING AND ADAPTIVE INTELLIGENT SYSTEMS (EAIS) Book Series: IEEE Conference on Evolving and Adaptive Intelligent Systems Published: 2014
- 0 0 0 0 0 0 0.00
- ☐ 76. **Simulated Annealing Approach to Fuzzy Modeling of Servo Systems**
- By: Precup, Radu-Emil; Radac, Mircea-Bogdan; Dragos, Claudia-Adina; et al.
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