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Online identification of evolving Takagi-Sugeno-Kang fuzzy models for crane systems

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Abstract

This paper suggests new evolving Takagi-Sugeno-Kang fuzzy models for crane systems. A set of evolving TSK fuzzy models with different parameters and a relatively simple and transparent implementation of an evolutionary algorithm to guide modeling is proposed on the basis of the fuzzy inference factors after the first step of the online identification algorithm. The rule bases and parameters which continuously evolve are updated in power and by modifying existing rules and parameters. The algorithm is applied in the framework of a crane control equipment. The evolving TSK fuzzy models are tested

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with other TSK fuzzy models and modeling approach the proposed evolving TSK fuzzy models are simple data and that these models outperform other TSK fuzzy models reserved.

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