

## Aspects Concerning the Tuning of 2-DOF Fuzzy Controllers

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**Abstract** – The paper presents aspects concerning the tuning of two-degree-of-freedom (2-DOF) fuzzy controllers focused on 2-DOF PI-fuzzy controllers and 2-DOF PID-fuzzy controllers. 2-DOF Mamdani and Takagi-Sugeno fuzzy control system structures are offered. The tuning is based on mapping the parameters of the linear PI and PID controllers to the parameters of the fuzzy controllers in terms of the modal equivalence principle. The linear controllers are tuned by Preitl's and Precup's Extended Symmetrical Optimum method. Some experimental results dealing with the speed control of a servo system are given.

**Key words:** 2-DOF PI-fuzzy controllers, 2-DOF PID-fuzzy controllers, PI controllers, PID controllers

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# SAUM 2010 CONFERENCE

## PRELIMINARY PROGRAM

### SESSIONS OVERVIEW

Wednesday, November 10, 2010		
<i>Time</i>	<i>Activities</i>	<i>Place</i>
10:00 – 11:00	Registration	
11:00 – 12:00	Opening Ceremony	
12:00 – 13:00	Cocktail	
13:00 – 14:30	<b>Session A: ROBOTICS I</b>	Room 1
14:45 – 16:15	<b>Session B: INTELLIGENT CONTROL</b>	Room 1
16:30 – 18:30	<b>Session C: NONLINEAR SYSTEMS</b>	Room 1

Thursday, November 11, 2010		
<i>Time</i>	<i>Activities</i>	<i>Place</i>
10:00 – 11:30	<b>Session D: HYDRAULIC SYSTEMS</b>	Room 1
10:00 – 11:30	<b>Session E: ROBOTICS II</b>	Room 2
12:00 – 14:00	<b>Session F: INFORMATION AND COMMUNICATION TECHNOLOGIES I</b>	Room 1
12:00 – 14:00	<b>Session G: INDUSTRIAL AND PROCESS CONTROL I</b>	Room 2
15:00 – 17:00	<b>Session H: MEASUREMENT AND INSTRUMENTATION I</b>	Room 1
15:00 – 17:00	<b>Session I: GEOGRAPHIC INFORMATION SYSTEMS, WIRELESS SENSOR NETWORKS AND WEB</b>	Room 2
15:00 – 17:00	<b>Session J: FUZZY CONTROL</b>	Room 3
20:00	Gala Dinner	

Friday, November 12, 2010		
<i>Time</i>	<i>Activities</i>	<i>Place</i>
10:00 – 12:00	<b>Session K: INFORMATION AND COMMUNICATION TECHNOLOGIES II</b>	Room 1
10:00 – 12:00	<b>Session L: MEASUREMENT AND INSTRUMENTATION II</b>	Room 2
10:00 – 12:00	<b>Session M: INDUSTRIAL AND PROCESS CONTROL II</b>	Room 3
12:30 – 15:00	<b>Session N: APPLIED MATHEMATICS AND MECHANICS</b>	Room 1
12:30 – 15:00	<b>Session O: SYSTEM IDENTIFICATION AND MODELING</b>	Room 2
15:00	Closing Ceremony	

**Session I: GEOGRAPHIC INFORMATION SYSTEMS, WIRELESS SENSOR NETWORKS AND WEB**

*Chairpersons: J. Žunić, D. Janković*

Session I	I1 • Invited paper
<b>R. Arnaudov, L. Stoimenov</b> SENSOR WEB FOR MONITORING AND CONTROL OF POWER SUPPLY NETWORKS	
Session I	I2 • Regular paper
<b>Č. Vasić, D. Rančić, B. Predić, D. Mitić</b> ONE APPROACH TO DYNAMIC RELOCATION OF EMERGENCY AMBULANCE VEHICLES BASED ON GIS	
Session I	I3 • Regular paper
<b>J. Trpovski, E. Lazarevska</b> A REAL-TIME GPS BASED VEHICLE TRACKING, NAVIGATING AND MONITORING SYSTEM	
Session I	I4 • Regular paper
<b>P. Balzhiev, I. Dochev, N. Stoyanov, R. Arnaudov</b> WIRELESS SENSOR NETWORK FOR MONITORING THE MICROCLIMATE IN BIG PUBLIC BUILDINGS AND COMPLEXES	
Session I	I5 • Regular paper
<b>K. Benkić, M. Malajner, Ž. Čučej</b> UNSLOTTED CSMA/CA IN IEEE 802.15.4: PERFORMANCE AND ITS LIMITATIONS	
Session I	I6 • Regular paper
<b>M. Malajner, P. Planinšič, K. Benkić, Ž. Čučej</b> UNCERTAINTY OF TWO-RAY PROPAGATION MODEL USING IN WSN LOCALIZATION	

**Session J: FUZZY CONTROL**

*Chairpersons: V. Kh. Pshikhopov, Ž. Čojbašić*

Session J	J1 • Invited paper
<b>S. Preitl, R. Precup, Z. Preitl</b> ASPECTS CONCERNING THE TUNING OF 2-DOF FUZZY CONTROLLERS	
Session J	J2 • Regular paper
<b>S. Jovanović, M. Milovanović, M. Matijević</b> FUZZY LOGIC CONTROLLER DESIGN FOR SEMI-ACTIVE VEHICLE SUSPENSION SYSTEMS	
Session J	J3 • Regular paper
<b>D. Lazić, Z. Čojbašić, M. Ristanović</b> GENETIC OPTIMIZATION OF CONVENTIONAL AND FUZZY ELECTROMECHANICAL AEROFIN CONTROL	
Session J	J4 • Regular paper
<b>V. M. Ojleska, T. Kolemishvska-Gugulovska, G. M. Dimirovski</b> INFLUENCE OF THE STATE SPACE PARTITIONING INTO REGIONS WHEN DESIGNING SWITCHED FUZZY CONTROLLERS	